

Stateless encoders: VP8

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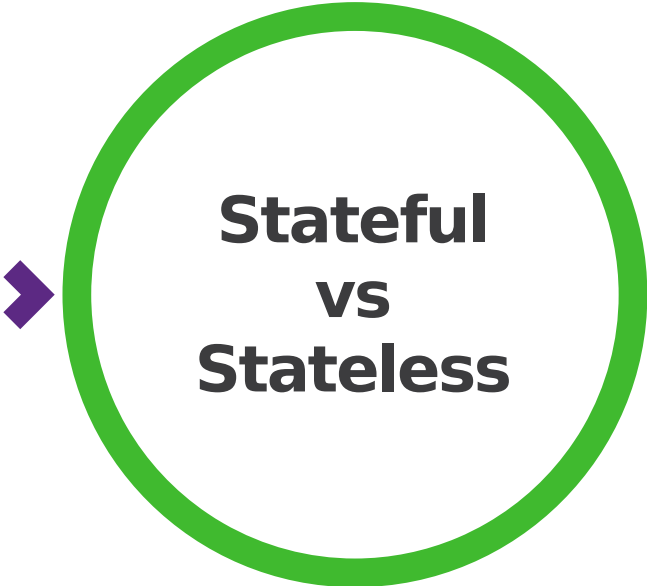
Agenda

- Definitions
- uAPI (VP8 RFC)
- Rate control (VP8 RFC)
- Challenges





Definitions

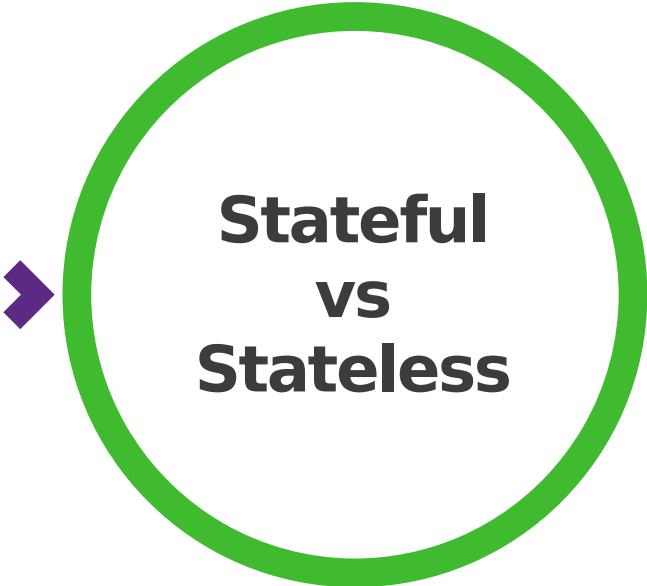


Stateful VS Stateless

Stateful	Stateless
State kept and maintained in hardware	State kept and maintained outside hardware

So what?





Stateful vs Stateless

Stateful	Stateless
More complex hw	Less complex hw
Sw needs to interact with codec firmware	More registers to cope with
More expensive context change	Less expensive context change
Less flexibility	More flexibility



uAPI

First encoders

- 2020: H.264
 - <https://github.com/bootlin/linux/tree/hantro/h264-encoding-v5.11>
 - <https://github.com/bootlin/v4l2-hantro-h264-encoder>
- 2023: VP8
 - <https://lore.kernel.org/linux-arm-kernel/20230309125651.23911-1-andrzej.p@collabora.com/T/>
 - <https://gitlab.collabora.com/linux/for-upstream/-/tree/vp8-rfc-v6.4-rc6>
 - https://gitlab.freedesktop.org/gstreamer/gstreamer/-/merge_requests/3736

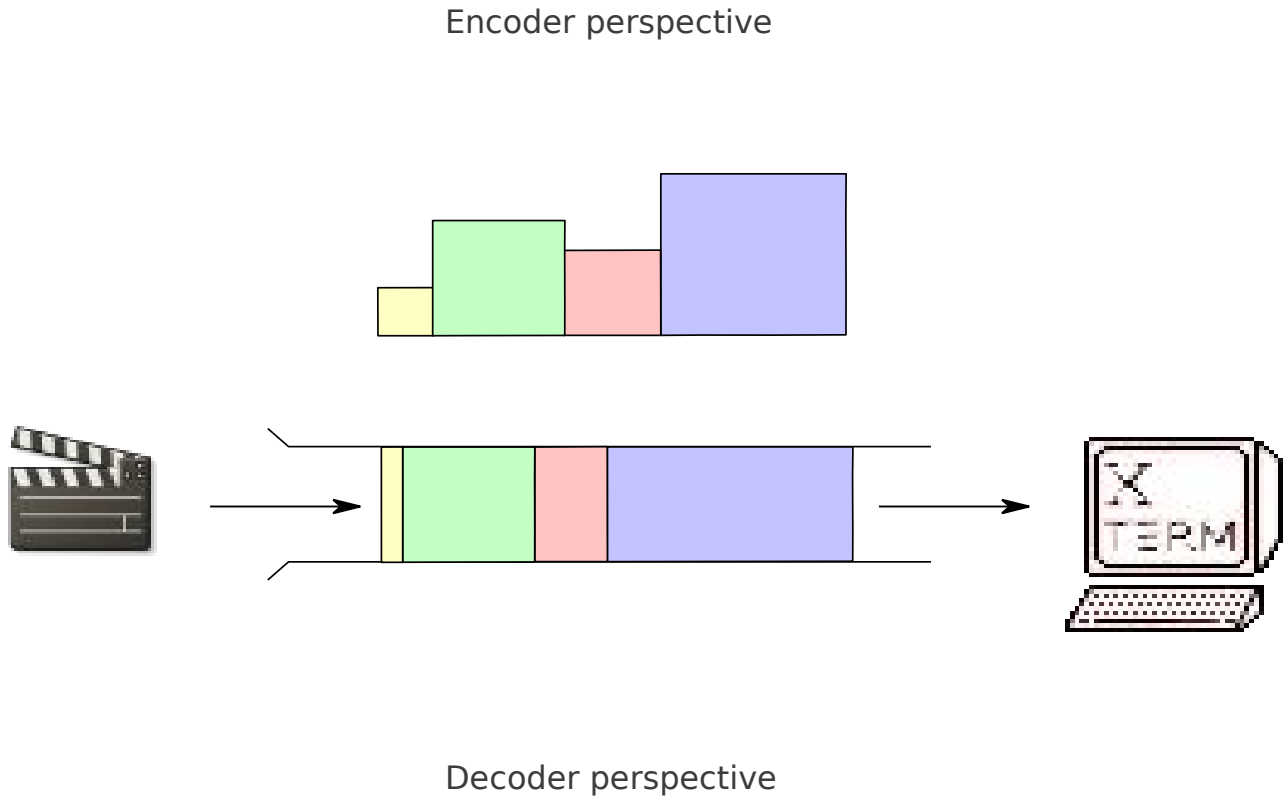


uAPI decisions (VP8 RFC)

- Request API
- Frame header built by the kernel
- GOP length decided by userspace
- Single reference frame (simple!)



Rate control



uAPI decisions (VP8 RFC)

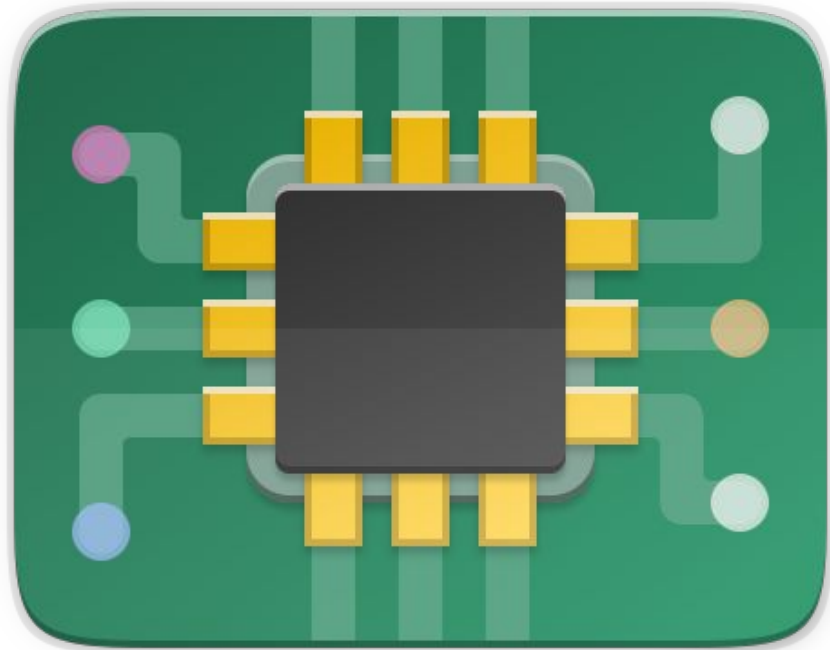
- Per-frame constant QP
- Dedicated QP control





Challenges

➤ **More VP8 hw?**



Challenges

- How we review the new uAPI and drivers
- How (not?)to obey the “2 drivers rule”
- Where should frame header be assembled (kernel/user)?
- More than 1 reference frame
- Unify QP range?
- Compliance testing?

Challenges cont'd

- Rate control
 - Stateful!
 - But: opt-in for hardware-specific mechanisms
 - But: per-frame constant QP for userspace
- ROI from stateful uAPI?

AI?

- Possible use
 - Reference frame selection
 - Rate control
- Requirements
 - Looking at reconstructed buffer?





Thank you!



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